



1200 W motor control power board based on STGIB10CH60TS-L SLLIMM™ 2nd series IPM





Product summary	
STEVAL-IPM10B compact motor drive power board	STEVAL-IPM10B
STGIB10CH60TS-L SLLIMM™ 2nd series IPM	STGIB10CH60TS-L

Features

Input voltage: 125 - 400 V_{DC}
 Nominal power: up to 1200 W
 Nominal current: up to 7 A

- Input auxiliary voltage: up to 20 V DC
- Single- or three- shunt resistors for current sensing (with sensing network)
- · Two options for current sensing: dedicated op-amps or through MCU
- Overcurrent hardware protection
- IPM temperature monitoring and protection
- Hall sensor or encoder input
- Uses the STGIB10CH60TS-L IGBT intelligent power module from the 2nd series
 of SLLIMM™ IPMs
- Motor control connector (32-pin) to interface with ST MCU boards
- · Universal conception for further evaluation with breadboard and testing pins
- Very compact size
- · RoHS compliant

Description

The STEVAL-IPM10B is a compact motor drive power board based on the SLLIMM™ (small low-loss intelligent molded module) 2nd series module STGIB10CH60TS-L. It provides an affordable, easy-to-use solution for driving high power motors for a wide range of applications such as white goods, air conditioners, compressors, power fans, high-end power tools, and generally 3-phase inverters for motor drives. The IPM itself consists of short-circuit rugged IGBTs and a wide range of features including undervoltage lockout, smart shutdown, temperature sensing and NTC inside, and overcurrent protection.

The main characteristics of this evaluation board are its small size, minimal BOM and high efficiency. It consists of an interface circuit (BUS and $V_{\rm CC}$ connectors), bootstrap capacitors, snubber capacitor, hardware short-circuit protection, fault event signal, temperature monitoring. In order to increase its flexibility, it was designed to work in single or three-shunt configuration and with double current sensing options such as three dedicated op-amps on-board, or op-amps embedded on MCU. Hall/Encoder part completes the circuit.

Thanks to these advanced characteristics, the system has been specifically designed to achieve accurate and fast conditioning of the current feedback, matching the typical requirements for field-oriented control (FOC).

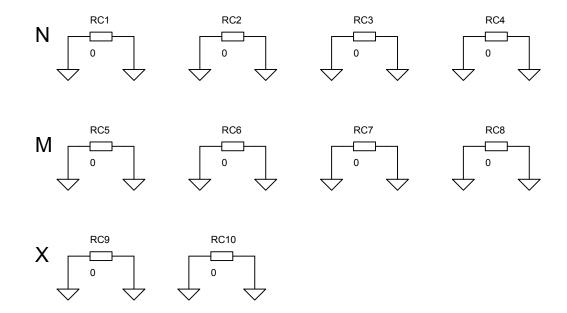
The STEVAL-IPM10B is compatible with ST's STM32-based control board, providing a complete platform for motor control.



1 Schematic diagram

Figure 1. STEVAL-IPM10B circuit schematic (1 of 6)

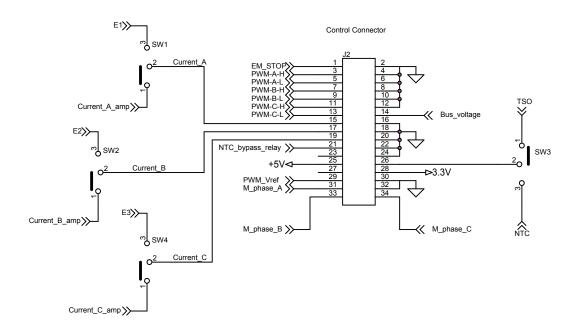
STEVAL-IPMnmx decoder

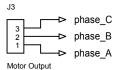


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Figure 2. STEVAL-IPM10B circuit schematic (2 of 6)





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Input

DC_bus_voltage

+Bus

R1
470K

A70K

D1
BAT48JFILM

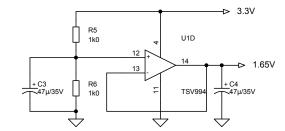
Bus_voltage

R2
470K

R3 120R

C2
10n

Figure 3. STEVAL-IPM10B circuit schematic (3 of 6)



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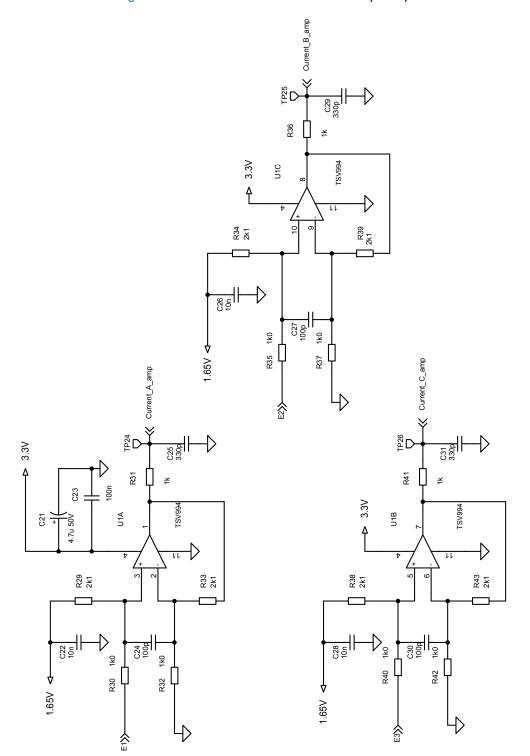


Figure 4. STEVAL-IPM10B circuit schematic (4 of 6)

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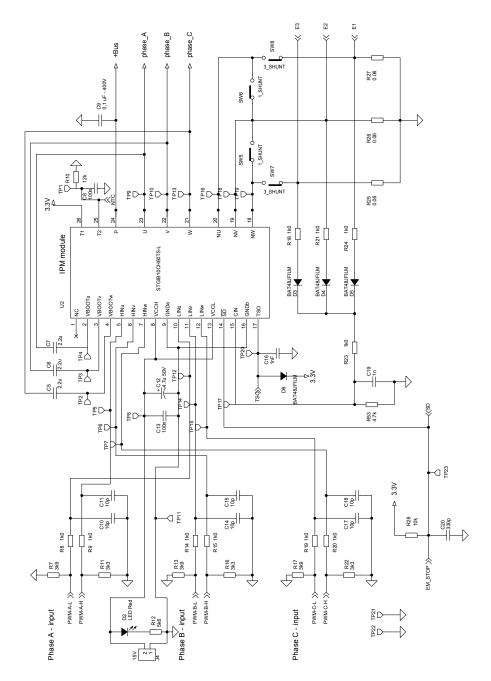


Figure 5. STEVAL-IPM10B circuit schematic (5 of 6)

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M_phase_C M_phase_A M_phase_B SW15 R52 4k7 SW14 R51 4k7 SW13 R50 4k7 R46 J 4k7 C37 10p C36 10p R45 4K7 R44 4K7 C35 Hall/Encoder 2k4 2k4 2k4 SW12 SW11 **R**48 R47 R49 100n က<mark>ြ</mark> SW16 6MS <mark>Q</mark> Encoder/Hall 100 100 100 100 100 H1/A+ H2/B+ H3/Z+ + 3.3/5V GND +5∨4

Figure 6. STEVAL-IPM10B circuit schematic (6 of 6)

3.3V

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Revision history

Table 1. Document revision history

Date	Version	Changes
12-Nov-2015	1	Initial release.
24-Feb-2016	2	Updated: figure 1 and figure 3.
24-May-2018	3	Updated: title, features and figure 5.
13-Sep-2019	4	Updates: Figure 3. STEVAL-IPM10B circuit schematic (3 of 6)Figure 4. STEVAL-IPM10B circuit schematic (4 of 6)

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